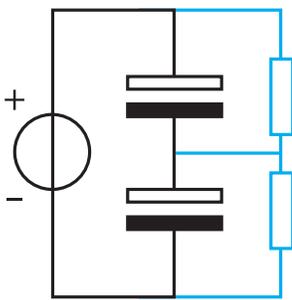


In the design of a capacitor bank, it is important to balance the capacitors for both DC and transient signal.

If two capacitors are placed in parallel to a DC voltage source U , the midpoint-voltage is not automatically $0.5 \cdot U$. The voltage distribution is dominated by the leakage current, which varies by capacitor and is voltage-dependent. The capacitor that has the larger leakage current at $0.5 \cdot U$ will have a somewhat smaller voltage drop than the parallel part, leading to an equalized leakage current through both parts.

1. DC Balancing



Drawing 1

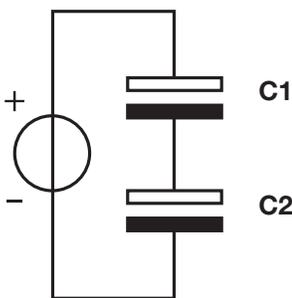
Depending on the difference in leakage current, this could lead to voltage drops larger than the rated voltage, which could result in decreased lifetime or even early failure.

Balancing the DC voltage is therefore necessary. This can be done in a passive way as shown in Drawing 1: two resistors in parallel to the capacitors, with values typically calculated as $R_{\max} = (2 \cdot U_{\max} - U) / I_{\text{leak-5min}} \cdot U_{\max}$ would be the maximum allowable voltage drop across one part (typically U_{rated}). U is the applied DC voltage. $I_{\text{leak-5min}}$ is the DC leakage current as measured after five minutes of applied rated voltage.

The disadvantage of this way of passive balancing is a relatively high efficiency loss, typically from 1 % to 5 %. This is unacceptable in applications like solar inverters, where the need for maximum efficiency dominates the market. Here designers work with active balancing.

Practical advice: if one of the capacitors in a parallel connection fails, replace both capacitors with two fresh ones from the same batch, to ensure that the leakage currents of both devices in one branch are roughly equal.

2. Transient Balancing



Drawing 2

Two capacitors in series connected to a power source will react differently to transient signals. For the change in voltage drop over a capacitor, $C1$ holds $\Delta V1 = 1/C1 \int I1(t) \cdot dt$. With a fixed current ($I=I1=I2$) running through $C1$ and $C2$, we get $C1 \cdot \Delta V1 = C2 \cdot \Delta V2$, or $\Delta V1/\Delta V2 = C2/C1$. So the change in midpoint voltage is determined by the ratio of the capacitances. This leads to simple requirements from designers: $C1 = C2$. This is correct from a theoretical point of view, but manufacturers of electrolytic capacitors work with a typical production variation of $\pm 20 \%$ in capacitance in their specifications. This tolerance is set on all produced parts; within one batch, variation is less. Typically, the variation within one batch is $\pm 6 \%$ (total spread from a minimum to maximum capacitance of 12%).

Practical advice: use parts from the same production batch per individual branch. When switching to another production batch, one should measure the 100 Hz capacitance value of all capacitors in that specific branch to exclude unbalanced branches. The same holds for the replacement of parts at failure. Remove all capacitors from the branch and replace with fresh ones from the same batch.