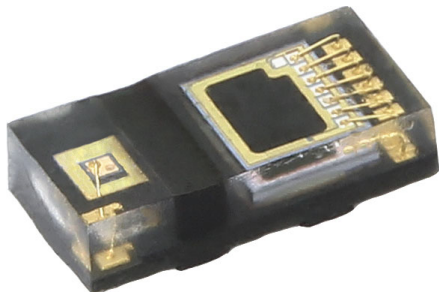


# A Small Package Proximity Sensor With a VCSEL, Low Idle Current, I<sup>2</sup>C Interface, and Smart Dual Slave Address



## LINKS TO ADDITIONAL RESOURCES



3D Models



Application Notes



Infographics

## DESCRIPTION

The VCNL36828P is a compact and versatile solution with an integrated vertical-cavity surface-emitting laser (VCSEL) and proximity sensor (PS). It incorporates photo diodes, amplifiers, and analog-to-digital converting circuits using CMOS technology into a single package. The VCNL36828P has been developed for proximity detection applications that require a dual slave address, low power consumption, small package size, small window size, and short range operation. In addition, given the typical rated supply voltage of 1.8 V to reduce power consumption, the sensor is intended for battery-powered applications.

## FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 2.0 x 1.0 x 0.5
- Integrated modules: vertical-cavity surface-emitting laser (VCSEL) and a proximity sensor (PS)
- 1.8 V rated power supply and I<sup>2</sup>C bus
- Low power consumption with 5  $\mu$ A idle current
- A small package allows a design with a small window size
- Smart dual I<sup>2</sup>C slave address in one package
- Immunity to red glow (940 nm VCSEL)
- Programmable I<sub>VCSEL</sub> sink current
- Intelligent cancellation to reduce cross talk phenomenon
- Smart persistence scheme to reduce measurement response time
- Interrupt functionality
- Material categorization: for definitions of compliance please see [www.vishay.com/doc?99912](http://www.vishay.com/doc?99912)



**RoHS**  
COMPLIANT  
**HALOGEN**  
**FREE**  
**GREEN**  
(5-2008)

## APPLICATIONS

- [Force feedback applications](#)
- Smartphones and true wireless stereo (TWS) earbuds
- VR / AR headsets and smart glasses
- Smartwatches
- Touchless button / dispensing
- [Hygienic applications](#)

## PRODUCT SUMMARY

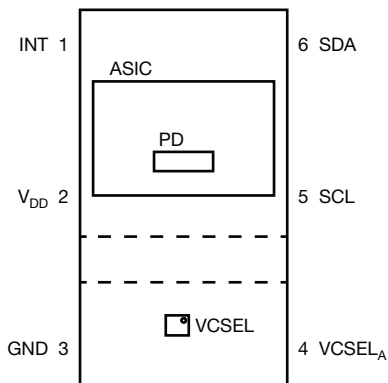
PART NUMBER	OPERATING RANGE (mm)	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	MAX. VCSEL DRIVING CURRENT (mA)	OUTPUT CODE	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT
VCNL36828P	200	1.65 to 2.00	1.2 to 3.6	20	12 bit / 16 bit, I <sup>2</sup> C	16 bit / -

## ORDERING INFORMATION

ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS
VCNL36828P	Tape and reel	MOQ: 5000 pcs, 5000 pcs/reel	2.0 mm x 1.0 mm x 0.5 mm

### Note

<sup>(1)</sup> MOQ: minimum order quantity

**PIN DEFINITION**


PIN DESCRIPTION			
PIN NUMBER	PIN NAME	TYPE	DESCRIPTION
1	INT	O (open drain)	Interrupt
2	V <sub>DD</sub>	I	Supply voltage
3	GND	I	Ground
4	VCSEL <sub>A</sub>	I	VCSEL anode
5	SCL <sup>(1)</sup>	I / O (open drain)	I <sup>2</sup> C serial clock
6	SDA <sup>(1)</sup>	I / O (open drain)	I <sup>2</sup> C serial data

**Note**

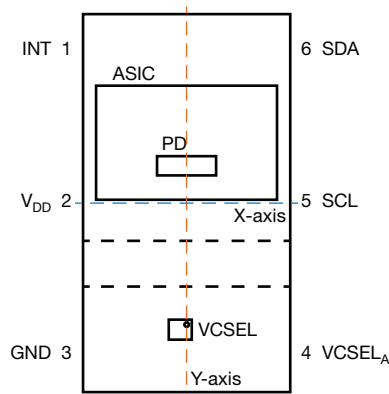
<sup>(1)</sup> Pin 5 (SCL) and pin 6 (SDA) can be swapped to change the slave address from 0x60 to 0x51; please refer to Table 1

ABSOLUTE MAXIMUM RATINGS (T <sub>amb</sub> = 25 °C, unless otherwise specified)					
PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT
Supply voltage		V <sub>DD</sub>	0	2	V
Ambient temperature range		T <sub>amb</sub>	-40	+85	°C
Storage temperature range		T <sub>stg</sub>	-40	+100	°C

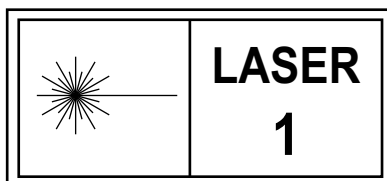
<b>BASIC CHARACTERISTICS</b> ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)						
PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
<b>ASIC</b>						
Supply voltage		$V_{DD}$	1.65	1.80	2.00	V
Supply current <sup>(1)</sup>	Shutdown state; light condition = dark; $V_{DD} = 1.8\text{ V}$	$I_{DD}$	-	1	-	$\mu\text{A}$
	Idle state <sup>(2)</sup> ; $V_{DD} = 1.8\text{ V}$		-	5	-	
	Active state <sup>(2)</sup> ; $V_{DD} = 1.8\text{ V}$		-	330	-	
I <sup>2</sup> C supply voltage		$V_{PULL\ UP}$	1.2	1.8	3.6	V
I <sup>2</sup> C signal input, logic high	$V_{DD} = 1.8\text{ V}$	$V_{IH}$	1	-	-	V
I <sup>2</sup> C signal input, logic low	$V_{DD} = 1.8\text{ V}$	$V_{IL}$	-	-	0.5	V
<b>VCSEL</b>						
Supply voltage of the VCSEL <sup>(3)</sup>		$V_{VCSEL}$	2.62	-	3.60	V
Forward voltage	$I_F = 9\text{ mA}$	$V_F$	-	1.92	-	V
Forward current		$I_F$	7	-	20	mA
Angle of half intensity		$\phi$	-	$\pm 4.5$	-	$^{\circ}$
Peak wavelength	$I_F = 9\text{ mA}$	$\lambda_p$	-	940	-	nm
Spectral bandwidth	$I_F = 9\text{ mA}$	$\Delta\lambda$	-	3	-	nm
<b>PHOTODIODE</b>						
Angle of half sensitivity	X-axis <sup>(4)</sup>	$\phi$	-	$\pm 60$	-	$^{\circ}$
	Y-axis <sup>(4)</sup>		-	$\pm 45$	-	
Peak sensitivity wavelength		$\lambda_p$	-	850	-	nm

**Notes**

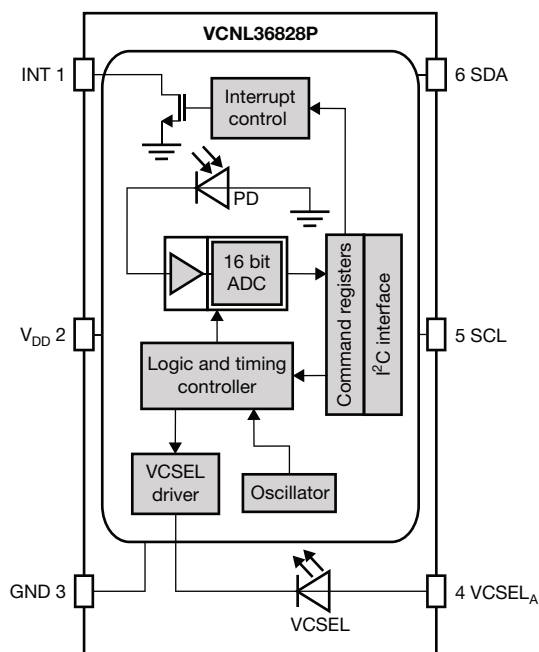
- (1) Actual current consumption depends on the register settings. Please refer to the application note on the current consumption
- (2) Excluding VCSEL driving current
- (3)  $V_{VCSEL}$  should at least match the minimum required supply voltage for the VCSEL  $V_{VCSEL, min}$ . Please refer to the  $V_{VCSEL, min}$  table
- (4) Cross section of the package



<b><math>V_{VCSEL, min}</math></b>								
PS_CURRENT ( $I_F$ )	7 mA	9 mA	11 mA	12 mA	15 mA	17 mA	19 mA	20 mA
$V_{VCSEL, min}$	2.62 V	2.74 V	2.86 V	2.91 V	3.08 V	3.19 V	3.3 V	3.36 V
$V_{VCSEL, max}$	3.6 V							

**LASER CLASS**

**Note**

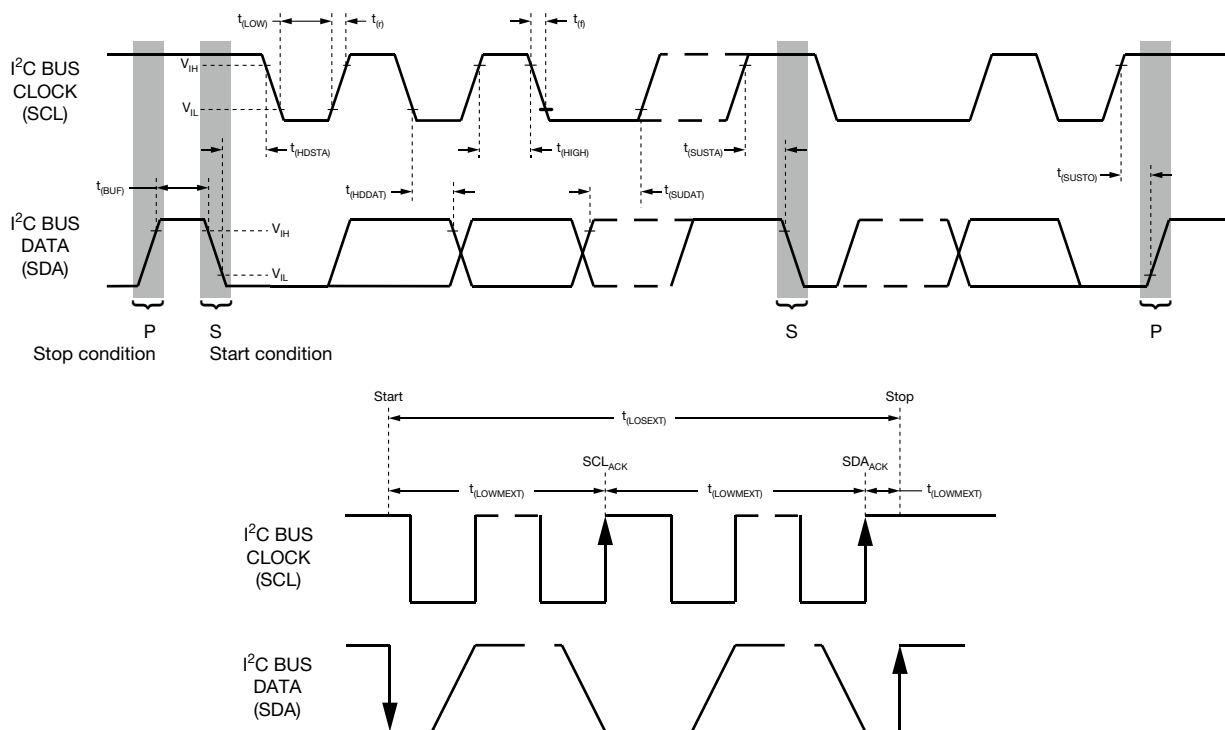
- Product specification with IEC / EN 60825-1:2014 compliance and above label

**BLOCK DIAGRAM**


<b>I<sup>2</sup>C BUS TIMING CHARACTERISTICS</b> ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)						
PARAMETER	SYMBOL	STANDARD MODE		FAST MODE		UNIT
		MIN.	MAX.	MIN.	MAX.	
Clock frequency	$f_{(I2CCLK)}$	10	100	10	400	kHz
Bus free time between start and stop condition	$t_{(BUF)}$	4.7	-	1.3	-	$\mu\text{s}$
Hold time after (repeated) start condition; after this period, the first clock is generated	$t_{(HDSTA)}$	4.0	-	0.6	-	$\mu\text{s}$
Repeated start condition setup time	$t_{(SUSTA)}$	4.7	-	0.6	-	$\mu\text{s}$
Stop condition setup time	$t_{(SUSTO)}$	4.0	-	0.6	-	$\mu\text{s}$
Data hold time	$t_{(HDDAT)}$	0	3450	0	900	ns
Data setup time	$t_{(SUDAT)}$	250	-	100	-	ns
I <sup>2</sup> C clock (SCL) low period	$t_{(LOW)}$	4.7	-	1.3	-	$\mu\text{s}$
I <sup>2</sup> C clock (SCL) high period	$t_{(HIGH)}$	4.0	-	0.6	-	$\mu\text{s}$
Clock / data fall time	$t_{(f)}$	-	300	-	300	ns
Clock / data rise time	$t_{(r)}$	-	1000	-	300	ns

**Note**

- Data based on standard I<sup>2</sup>C protocol requirement, not tested in production


Fig. 1 - I<sup>2</sup>C Bus Timing Diagram



## PARAMETER TIMING INFORMATION

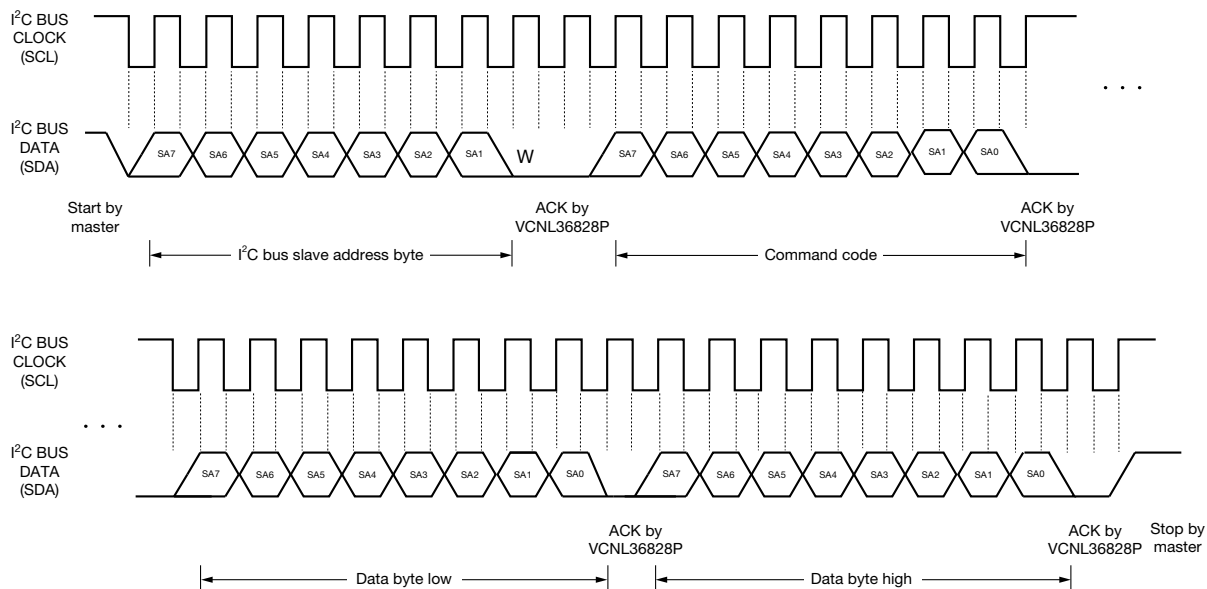


Fig. 2 - I<sup>2</sup>C Bus Timing for Sending Word Command Format

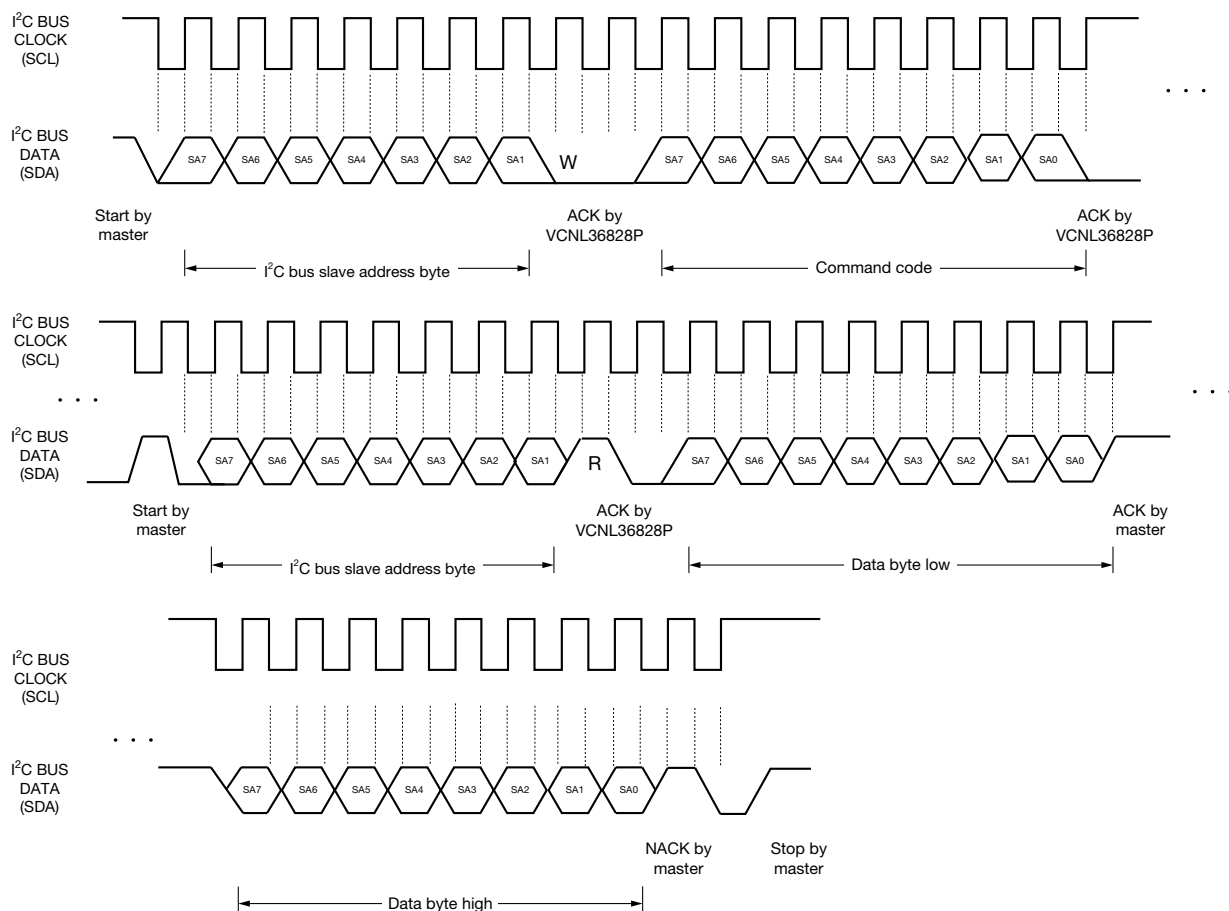


Fig. 3 - I<sup>2</sup>C Bus Timing for Receiving Word Command Format

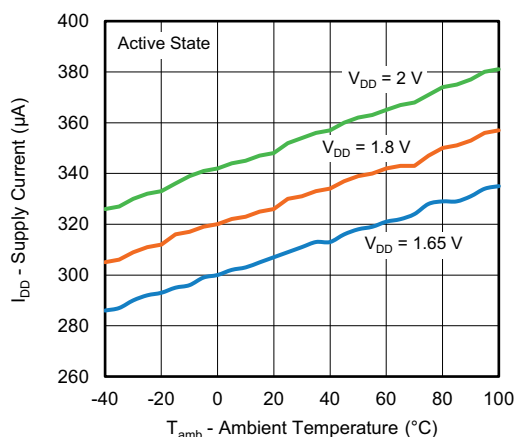
**TYPICAL PERFORMANCE CHARACTERISTICS** ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)


Fig. 4 - Supply Current vs. Ambient Temperature

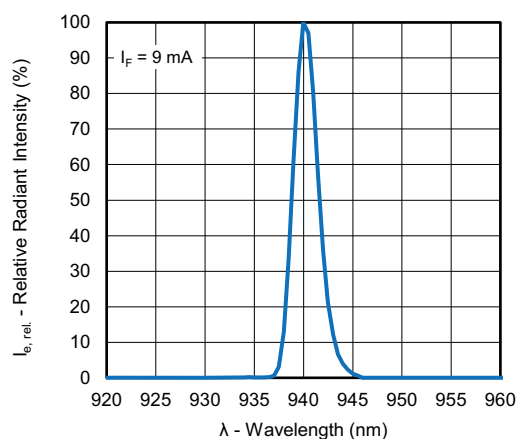


Fig. 7 - Relative Radiant Intensity vs. Wavelength of the VCSEL

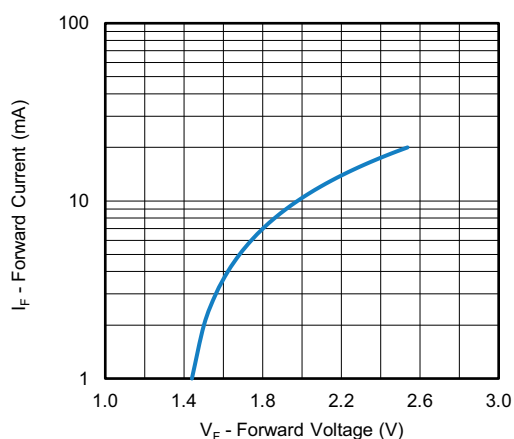


Fig. 5 - Forward Current vs. Forward Voltage of the VCSEL

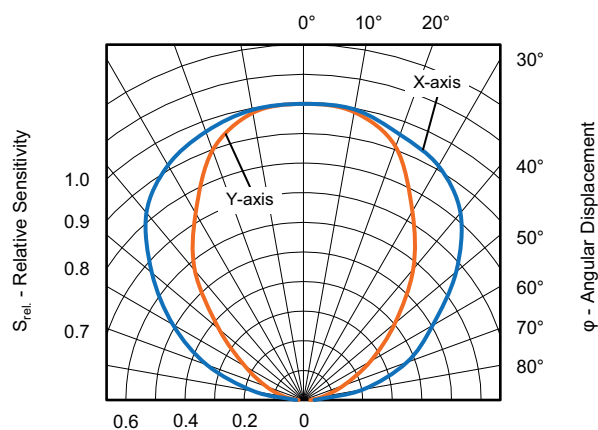


Fig. 8 - Relative Sensitivity vs. Angular Displacement of the Photodiode

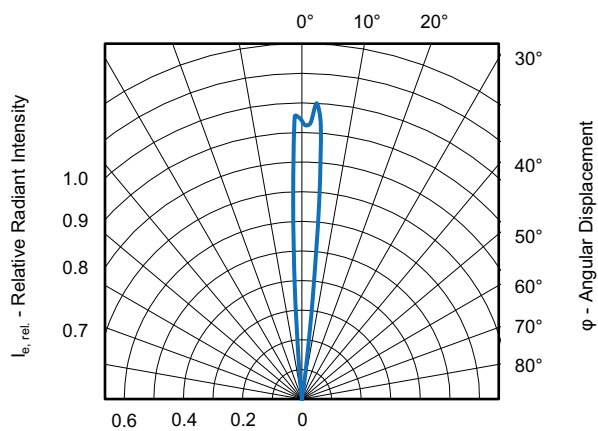


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement of the VCSEL

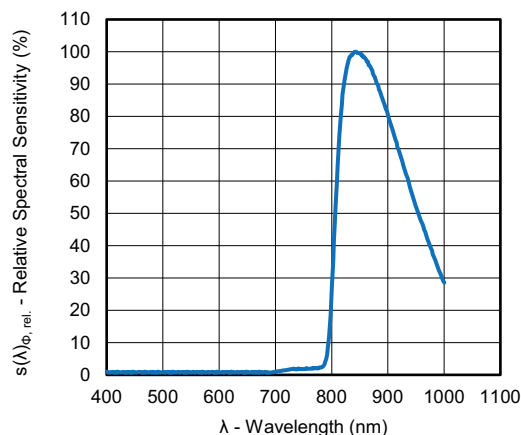


Fig. 9 - Relative Spectral Sensitivity vs. Wavelength of the Photodiode

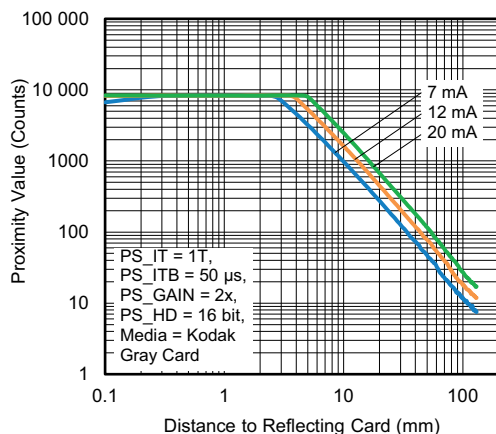


Fig. 10 - Proximity Value vs. Distance

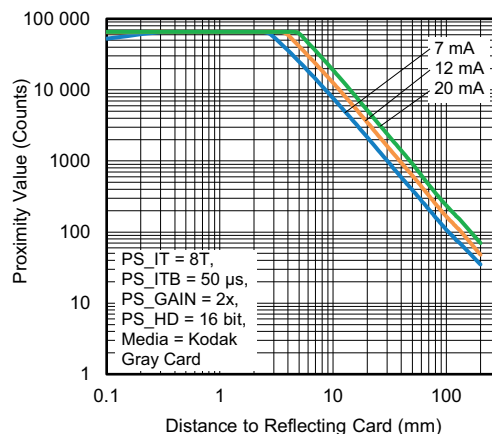


Fig. 11 - Proximity Value vs. Distance

## APPLICATION INFORMATION

### Slave Address Selection

The VCNL36828P supports a smart dual slave address where the designer can change the slave address by swapping the SCL and SDA pins, as shown in Table 1.

TABLE 1 - SLAVE ADDRESS TABLE				
PIN 5	PIN 6	7 BIT SLAVE ADDRESS	8 BIT SLAVE ADDRESS (WRITE)	8 BIT SLAVE ADDRESS (READ)
SCL	SDA	0x60	0xC0	0xC1
SDA	SCL	0x51	0xA2	0xA3

A smart dual slave address provides the flexibility for the designer to connect two devices from two different slave addresses on the same I<sup>2</sup>C bus. Besides that, the two slave address options allow designers to select a different slave address if one is used by the other slave devices on the same I<sup>2</sup>C bus in a single device application. To ensure more stable slave address recognition, especially in systems with higher noise levels, it is recommended to follow a specific power-on sequence: apply power to the I<sup>2</sup>C bus first, followed by V<sub>DD</sub>. This sequence helps the IC determine the correct slave address more reliably in noisy environments.

### Application Circuit With a Single Device - Slave Address 0x60

Fig. 12 shows an application circuit example with a single device. As described in Table 1, when pins 5 and 6 are connected to the clock and data signal from the microcontroller, as shown in Fig. 12, they will then be configured as an SCL pin and SDA pin, respectively. The 7 bit slave address option of 0x60 will be automatically selected.

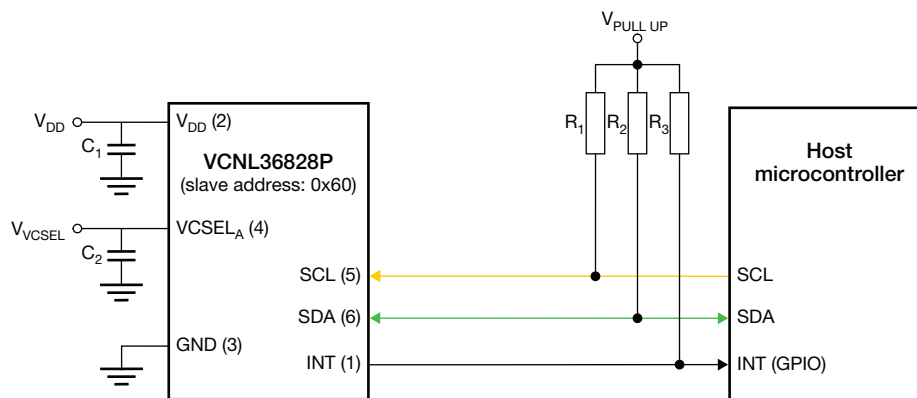


Fig. 12 - Application Circuit Example for a Single VCNL36828P - Slave Address 0x60

### Application Circuit With a Single Device - Slave Address 0x51

On the other hand, when pins 5 and 6 are connected to the data and clock signal from the microcontroller, as shown in Fig. 13, they will then be configured as an SDA pin and SCL pin, respectively. The 7 bit slave address option of 0x51 will be automatically selected.

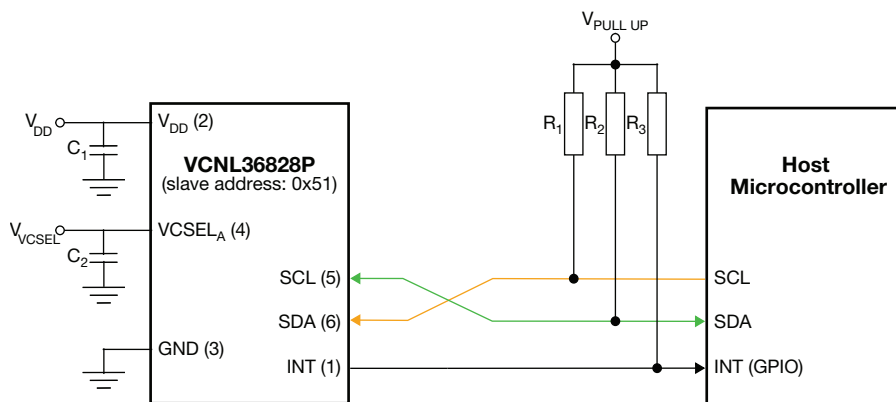


Fig. 13 - Application Circuit Example for a Single VCNL36828P - Slave Address 0x51

Table 2 shows the required values and the explanation for the individual application circuit parameters.

TABLE 2 - APPLICATION CIRCUIT PARAMETERS		
CIRCUIT PARAMETER	VALUE	DESCRIPTION
V <sub>DD</sub>	1.65 V to 2.00 V	A stable power supply such as a low dropout regulator or a switching regulator is required; the power supply isolation can be further improved with a decoupling capacitor C <sub>1</sub>
V <sub>VCSEL</sub>	2.62 V to 3.60 V	A stable power supply such as a low dropout regulator or a switching regulator that can supply an adequate amount of power (max. VCSEL pulse driving current of 20 mA) is required; the power supply isolation can be further improved with a decoupling capacitor C <sub>2</sub> ; the minimum voltage depends on the selected driving current of the VCSEL; please refer to Table V <sub>VCSEL, min.</sub> for reference
V <sub>PULL UP</sub>	1.2 V to 3.6 V	A stable power supply such as a low dropout regulator or a switching regulator is required; a voltage level shifter is required if the I <sup>2</sup> C bus voltage from the microcontroller is higher than 3.6 V
C <sub>1</sub> - C <sub>4</sub>	100 nF to 1 μF	Decoupling capacitors are recommended to reduce the noise in the supply voltage
R <sub>1</sub> - R <sub>2</sub>	2.2 kΩ to 4.7 kΩ	Pull-up resistors within the range of 2.2 kΩ to 4.7 kΩ are recommended; any increase in bus capacitance or resistance will increase the logic high transition time
R <sub>3</sub>	4.7 kΩ to 22 kΩ	Pull-up resistor within the range of 4.7 kΩ to 22 kΩ is recommended

### Application Circuit With a Smart Dual Slave Address

Fig. 14 shows an application circuit example with a smart dual slave address. By swapping the SCL and SDA pins of the second device, as shown in Table 1, the designer can change the 7 bit slave address of the VCNL36828P. This provides the flexibility for the designer to connect two devices from two different slave addresses on the same I<sup>2</sup>C bus.

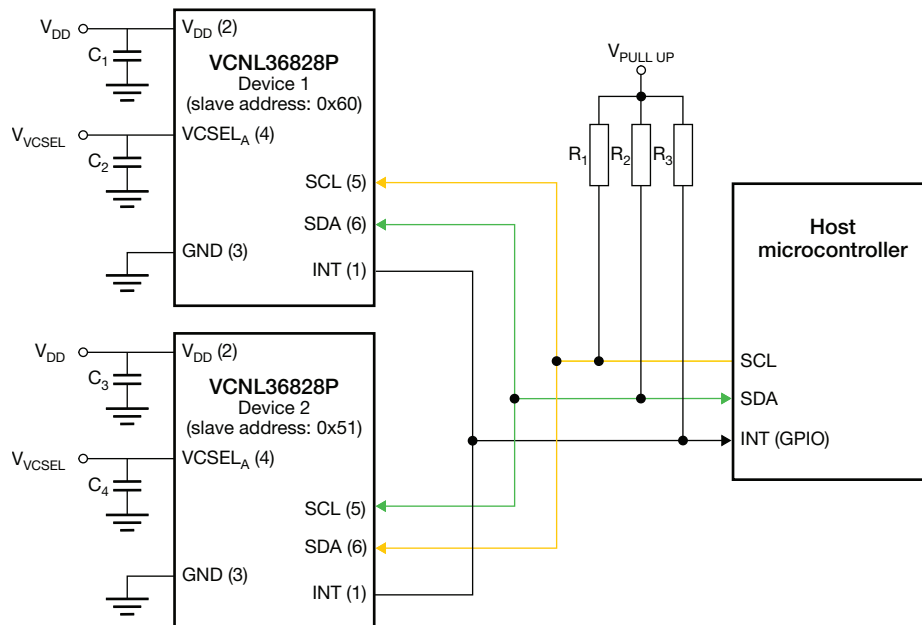
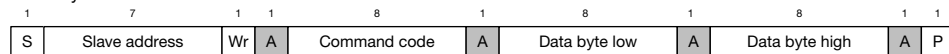


Fig. 14 - Application Circuit Example for Two VCNL36828Ps - Smart Dual Slave Address

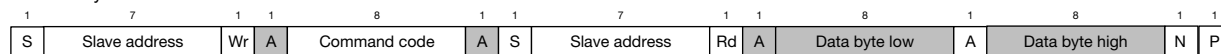
### I<sup>2</sup>C Write and Read Protocol

The communication with the VCNL36828P can be performed via I<sup>2</sup>C. The I<sup>2</sup>C write and read protocol when communicating with the proximity sensor is shown in Fig. 15.

Send byte → write command to VCNL36828P



Receive byte → read data from VCNL36828P



S = start condition

P = stop condition

A = acknowledge

N = not acknowledge

☐ Host action

☒ VCNL36828P response

Fig. 15 - I<sup>2</sup>C Write and Read Protocol

It is imperative that only the restart condition for the I<sup>2</sup>C read is implemented instead of the stop and restart condition.



## Function Description

**TABLE 3 - COMMAND CODE AND REGISTER DESCRIPTION**

COMMAND CODE	DATA BYTE LOW / HIGH	REGISTER NAME	DEFAULT VALUE	FUNCTION	ACCESS
0x00	L	PS_CONF1_L	0x00	Internal calibration setting	Write and read
				Switch the sensor on / off	
	H	PS_CONF1_H	0x00	High dynamic range setting	
				Persistence setting	
				Interrupt setting	
0x01	L	PS_CONF2_L	0x00	Measurement period setting	
				Signal strength setting (Integration time and multi-pulse)	
				High gain setting	
	H	PS_CONF2_H	0x00	Sensitivity of the ADC setting	
				Internal crosstalk cancellation setting	
0x02	L	PS_CONF3_L	0x00	VCSEL driving current setting	
				Sensor mode setting	
				Active force mode trigger setting	
	H	PS_CONF3_H	0x00	Short measurement period setting	
				Sunlight cancellation setting	
0x03	L	PS_THDL_L	0x00	Low threshold interrupt value setting (low byte)	Read only
	H	PS_THDL_H	0x00	Low threshold interrupt value setting (high byte)	
0x04	L	PS_THDH_L	0x00	High threshold interrupt value setting (low byte)	
	H	PS_THDH_H	0x00	High threshold interrupt value setting (high byte)	
0x05	L	PS_CANC_L	0x00	Offset count cancellation value setting (low byte)	
	H	PS_CANC_H	0x00	Offset count cancellation value setting (high byte)	
0xF8	L	PS_DATA_L	0x00	Proximity output data (low byte)	
	H	PS_DATA_H	0x00	Proximity output data (high byte)	
0xF9	L	Reserved	0x00 - 0xFF	Reserved	
	H	INT_FLAG	0x00	Interrupt flag	
0xFA	L	VCNL36828P_ID_L	0x28 / 0x29	Device ID Slave address: 0x60; ID = 0x28 Slave address: 0x51; ID = 0x29	Read only
	H	VCNL36828P_ID_H	0x01	Device ID	

**Notes**

- All of the reserved registers are used for internal test. These values must be kept constant
- (1) The default ID depends on the connection of the SCL and SDA pins on the VCNL36828P with the SCL and SDA pins on the host MCU. If pins 5 and 6 on the VCNL36828P are connected to the SCL and SDA pins on the host, the default value will be 0x28. On the other hand, if pins 5 and 6 on the VCNL36828P are connected to the SDA and SCL pins on the host, the default value will be 0x29. Please refer to Fig. 13



## Command Register Format

**TABLE 4 - REGISTER NAME: PS\_CONF1\_L**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_CAL	Reserved						PS_ON
<b>COMMAND CODE</b>					<b>0x00</b>		
Bit Name	Function		Bit	Value	Description		
PS_CAL	Enable / disable the internal calibration		7	0x0 (0b0)	Disable (default)		
				0x1 (0b1)	Enable		
Reserved	Reserved		6 : 1	0x00 (0b000000)	Should be kept default		
PS_ON	Switch the sensor on / off		0	0x0 (0b0)	Turn off the sensor (shutdown) (default)		
				0x1 (0b1)	Turn on the sensor		

**TABLE 5 - REGISTER NAME: PS\_CONF1\_H**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
Reserved	PS_HD	PS_SP_INT	PS_SMART_PERS	PS_PERS		PS_INT	
COMMAND CODE						0x00	
Bit Name		Function		Bit	Value	Description	
Reserved		Reserved		15	0x0 (0b0)	Should be kept default	
PS_HD		Enable / disable high dynamic range (12 bit / 16 bit) ADC output setting		14	0x0 (0b0)	Disable (12 bit) (default)	
					0x1 (0b1)	Enable (16 bit)	
PS_SP_INT		Enable / disable the sunlight protection mode interrupt setting		13	0x0 (0b0)	Disable (default)	
					0x1 (0b1)	Enable	
PS_SMART_PERS		Enable / disable the smart persistence setting when the interrupt event is triggered		12	0x0 (0b0)	Disable (default)	
					0x1 (0b1)	Enable	
PS_PERS		Set the amount of consecutive threshold crossing events necessary to trigger interrupt		11 : 10	0x0 (0b00)	1 time (default)	
					0x1 (0b01)	2 times	
					0x2 (0b10)	3 times	
					0x3 (0b11)	4 times	
PS_INT		Set the interrupt mode setting		9 : 8	0x0 (0b00)	Interrupt disable (default)	
					0x1 (0b01)	Logic high / low mode	
					0x3 (0b11)	Trigger by each high / low threshold event	

**TABLE 6 - REGISTER NAME: PS\_CONF2\_L**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_PERIOD		PS_IT		PS_MPS		PS_ITB	PS_GAIN
COMMAND CODE					0x01		
Bit Name		Function		Bit	Value	Description	
PS_PERIOD		Set the measurement period		7 : 6	0x0 (0b00)	50 ms, which translates into 20 measurement/s (default)	
					0x1 (0b01)	100 ms, which translates into 10 measurements/s	
					0x2 (0b10)	200 ms, which translates into 5 measurements/s	
					0x3 (0b11)	400 ms, which translates into 2.5 measurements/s	
PS_IT		Set the integration time for one measurement; the pulse length “T” is determined by PS_ITB		5 : 4	0x0 (0b00)	1 T (default)	
					0x1 (0b01)	2 T	
					0x2 (0b10)	4 T	
					0x3 (0b11)	8 T	
PS_MPS		Set the number of infrared signal pulses per measurement		3 : 2	0x0 (0b00)	1 pulse (default)	
					0x1 (0b01)	2 pulses	
					0x2 (0b10)	4 pulses	
					0x3 (0b11)	8 pulses	
PS_ITB		Set the pulse length “T” for PS_IT		1	0x0 (0b0)	T = 25 μs (default)	
					0x1 (0b1)	T = 50 μs	
PS_GAIN		Set the gain of the ADC		0	0x0 (0b0)	x 1 gain (default)	
					0x1 (0b1)	x 2 gain	

**TABLE 7 - REGISTER NAME: PS\_CONF2\_H**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
Reserved		PS_SENS	PS_OFFSET	Reserved	PS_CURRENT		
COMMAND CODE					0x01		
Bit Name		Function		Bit	Value	Description	
Reserved		Reserved		15 : 14	0x0 (0b00)	Should be kept default	
PS_SENS		Set the sensitivity of the ADC		13	0x0 (0b0)	Normal sensitivity (default)	
					0x1 (0b1)	High sensitivity	
PS_OFFSET		Enable / disable the internal crosstalk cancellation		12	0x0 (0b0)	Disable (default)	
					0x1 (0b1)	Enable	
Reserved		Reserved		11	0x0 (0b0)	Should be kept default	
PS_CURRENT		Set the VCSEL driving current		10 : 8	0x0 (0b000)	7 mA (default)	
					0x1 (0b001)	9 mA	
					0x2 (0b010)	11 mA	
					0x3 (0b011)	12 mA	
					0x4 (0b100)	15 mA	
					0x5 (0b101)	17 mA	
					0x6 (0b110)	19 mA	
					0x7 (0b111)	20 mA	

**TABLE 8 - MAXIMUM BIT RESOLUTION AND DIGITAL OUTPUT COUNTS**

BIT NAME		PS_IT = 1T	PS_IT = 2T	PS_IT = 4T	PS_IT = 8T
PS_HD = 0 (12 bit)	PS_GAIN = 0 (x1 gain)	12 bit / 4095 counts			
	PS_GAIN = 1 (x2 gain)				
PS_HD = 1 (16 bit)	PS_GAIN = 0 (x1 gain)	12 bit / 4095 counts	13 bit / 8191 counts	14 bit / 16 383 counts	15 bit / 32 767 counts
	PS_GAIN = 1 (x2 gain)	13 bit / 8191 counts	14 bit / 16 383 counts	15 bit / 32 767 counts	16 bit / 65 535 counts

**TABLE 9 - REGISTER NAME: PS\_CONF3\_L**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved		PS_TRIG	PS_MODE	Reserved			
<b>COMMAND CODE</b>				<b>0x02</b>			
Bit Name	Function		Bit	Value	Description		
Reserved	Reserved		7 : 6	0x0 (0b00)	Should be kept default		
PS_TRIG	Set the active force mode trigger; This bit will be reset to 0 after the measurement cycle		5	0x0 (0b0)	Off (default)		
				0x1 (0b1)	Trigger		
PS_MODE	Set the measurement mode of the sensor		4	0x0 (0b0)	Auto mode (default)		
				0x1 (0b1)	Active force mode		
Reserved	Reserved		3 : 0	0x0 (0b0000)	Should be kept default		

**TABLE 10 - REGISTER NAME: PS\_CONF3\_H**

Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
PS_SPERIOD		Reserved	PS_SC			Reserved	
COMMAND CODE					0x02		
Bit Name		Function		Bit	Value	Description	
PS_SPERIOD		Set the short measurement period		15 : 14	0x0 (0b00)	Disable the short period (follow PS_PERIOD setting) (default)	
					0x1 (0b01)	6.25 ms, which translates into 160 measurements/s	
					0x2 (0b10)	12.5 ms, which translates into 80 measurements/s	
					0x3 (0b11)	25 ms, which translates into 40 measurements/s	
Reserved		Reserved		13	0x0 (0b0)	Should be kept default	
PS_SC		Enable / disable the sunlight cancellation		12 : 10	0x0 (0b000)	Disable (default)	
					0x7 (0b111)	Enable	
Reserved		Reserved		9 : 8	0x0 (0b00)	Should be kept default	

**TABLE 11 - REGISTER NAME: PS\_THDL**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_THDL_L							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
PS_THDL_H							
COMMAND CODE				0x03			
Bit Name	Function		Bit	Value	Description		
PS_THDL_L	Set the low threshold interrupt value		7 : 0	0 to 65 535	Low byte		
PS_THDL_H			15 : 8		High byte		

**TABLE 12 - REGISTER NAME: PS\_THDH**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_THDH_L							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
PS_THDH_H							
COMMAND CODE				0x04			
Bit Name	Function		Bit	Value	Description		
PS_THDH_L	Set the high threshold interrupt value		7 : 0	0 to 65 535	Low byte		
PS_THDH_H			15 : 8		High byte		

**TABLE 13 - REGISTER NAME: PS\_CANC**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_CANC_L							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
Reserved				PS_CANC_H			
COMMAND CODE				0x05			
Bit Name	Function		Bit	Value	Description		
PS_CANC_L	Set the offset count cancellation value		7 : 0	0 to 4095	Low byte		
PS_CANC_H			11 : 8		High byte		
Reserved	Reserved		15 : 12	0x0 (0b0000)	Should be kept default		

**TABLE 14 - REGISTER NAME: PS\_DATA**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
PS_DATA_L							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
PS_DATA_H							
COMMAND CODE				0xF8			
Bit Name	Function		Bit	Value	Description		
PS_DATA_L	Read the proximity output data		7 : 0	0 to 65 535	Low byte		
PS_DATA_H			15 : 8		High byte		

**TABLE 15 - REGISTER NAME: INT\_FLAG**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
Reserved			PS_SPFLAG	Reserved		PS_IF_CLOSE	PS_IF_AWAY
<b>COMMAND CODE</b>					<b>0xF9</b>		
<b>Bit Name</b>	<b>Function</b>		<b>Bit</b>	<b>Value</b>	<b>Description</b>		
Reserved	Reserved		7 : 0	0x00 - 0xFF (0b00000000 - 0b11111111)	Should be kept default		
Reserved	Reserved		15 : 13	0x0 (0b000)	Should be kept default		
PS_SPFLAG	Read the sunlight protection mode interrupt event flag		12	0x0 (0b0)	No sunlight protection mode interrupt event flag		
				0x1 (0b1)	Sunlight protection mode interrupt event flag		
Reserved	Reserved		11 : 10	0x0 (0b00)	Should be kept default		
PS_IF_CLOSE	Read the high threshold crossing interrupt event flag		9	0x0 (0b0)	No high threshold crossing interrupt event flag		
				0x1 (0b1)	High threshold crossing interrupt event flag		
PS_IF_AWAY	Read the low threshold crossing interrupt event flag		8	0x0 (0b0)	No low threshold crossing interrupt event flag		
				0x1 (0b1)	Low threshold crossing interrupt event flag		

**TABLE 16 - REGISTER NAME: VCNL36828P\_ID**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VCNL36828P_ID_L							
Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8
VCNL36828P_ID_H							
<b>COMMAND CODE</b>					<b>0xFA</b>		
<b>Bit Name</b>	<b>Function</b>		<b>Bit</b>	<b>Value</b>	<b>Description</b>		
VCNL36828P_ID_L	Read the device ID		7 : 0	0x28 (0b00101000)	Device with a slave address of 0x60		
				0x29 (0b00101001)	Device with a slave address of 0x51		
VCNL36828P_ID_H			15 : 8	0x01 (0b00000001)	Should be kept default		

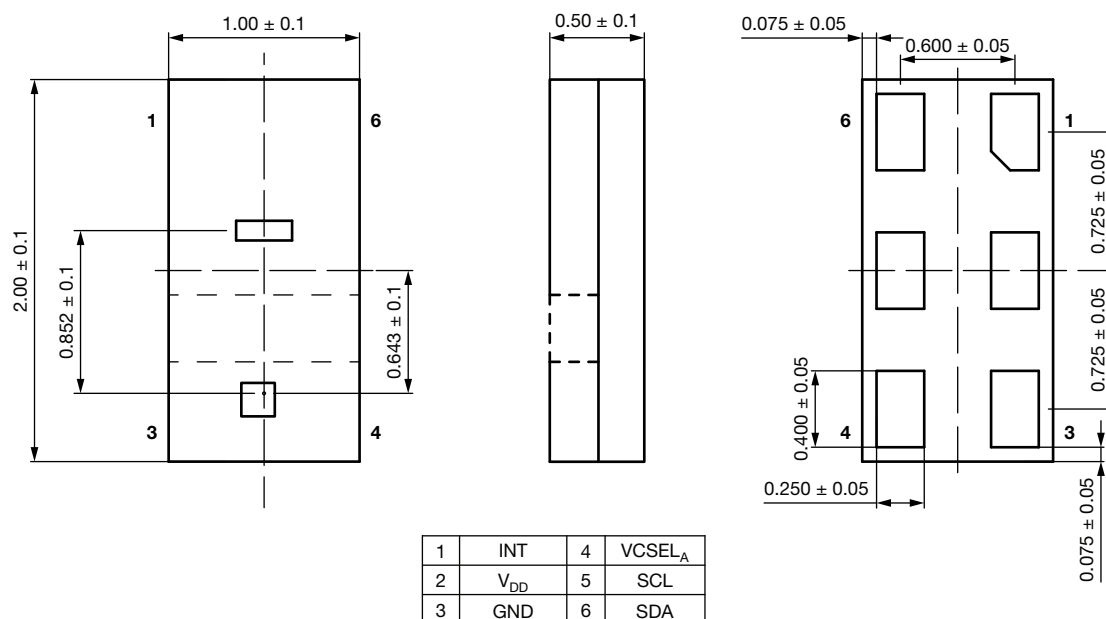
**PACKAGE INFORMATION** in millimeters


Fig. 16 - VCNL36828P Package Dimensions

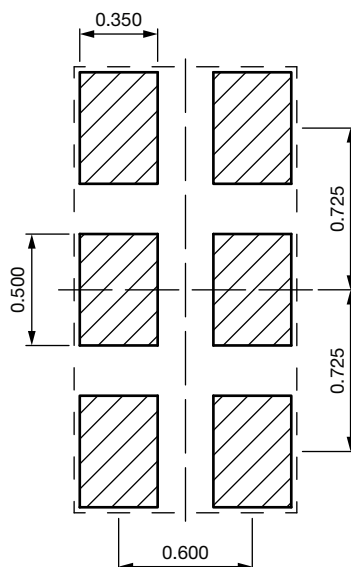
**RECOMMENDED LAYOUT PAD INFORMATION** in millimeters


Fig. 17 - VCNL36828P PCB Layout Footprint



## RECOMMENDED INFRARED REFLOW

Soldering conditions which are based on J-STD-020C

IR REFLOW PROFILE CONDITION			
PARAMETER	CONDITIONS	TEMPERATURE	TIME
Peak temperature		260 °C + 5 °C / - 5 °C (max.: 265 °C)	10 s
Preheat temperature range and timing		150 °C to 200 °C	60 s to 180 s
Timing within 5 °C to peak temperature		-	10 s to 30 s
Timing maintained above temperature / time		217 °C	60 s to 150 s
Timing from 25 °C to peak temperature		-	8 min (max.)
Ramp-up rate		3 °C/s (max.)	-
Ramp-down rate		6 °C/s (max.)	-

Recommend Normal Solder Reflow is 235 °C to 265 °C

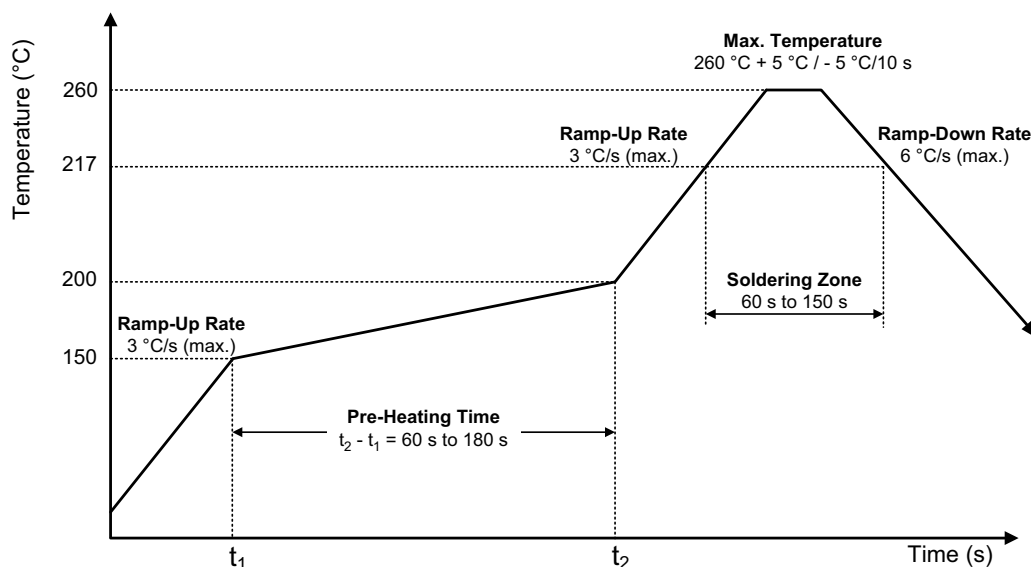
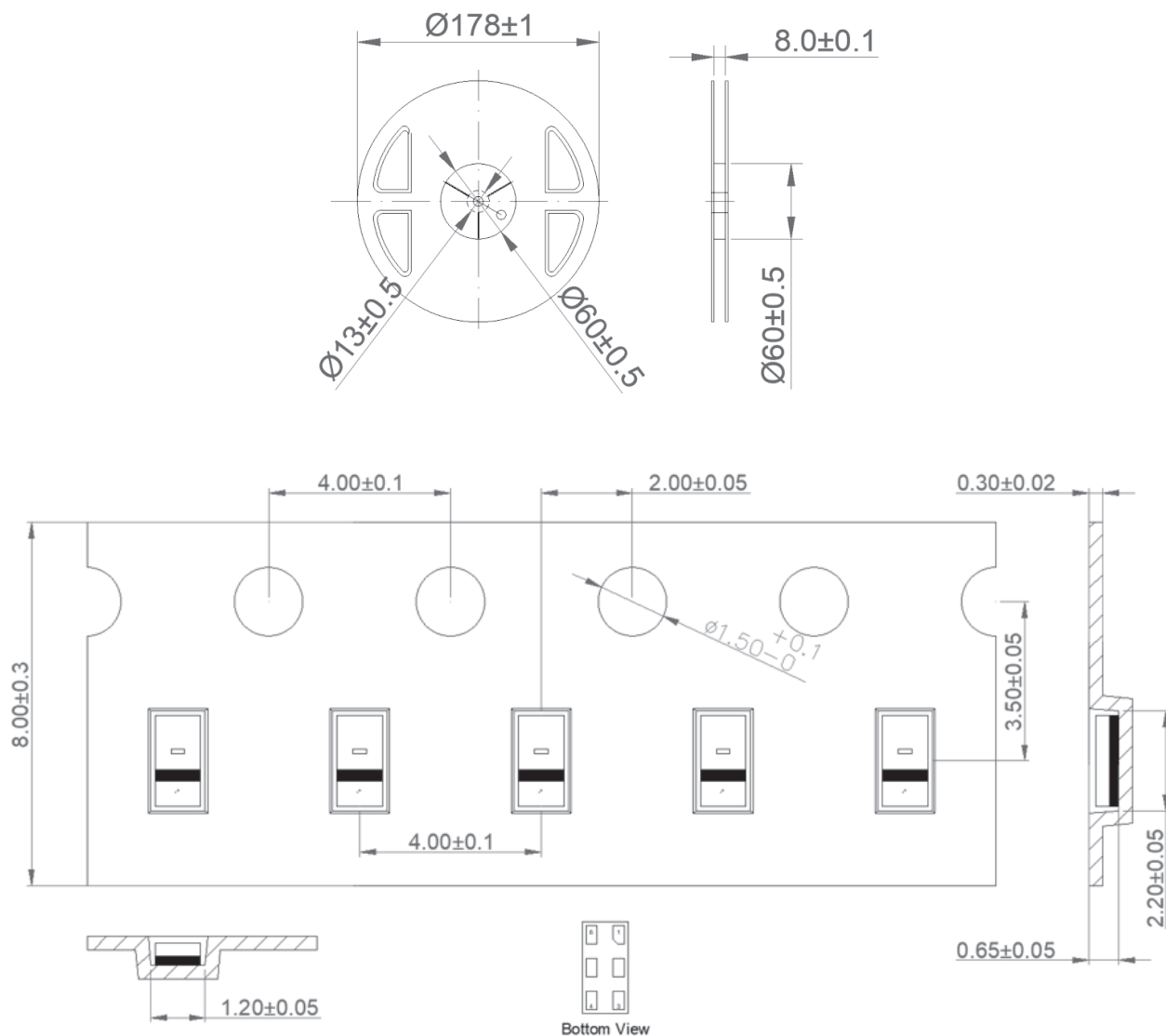


Fig. 18 - VCNL36828P Solder Reflow Profile Chart



**TAPE PACKAGING INFORMATION** in millimeters





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