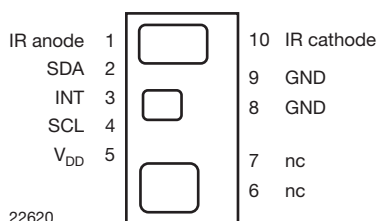
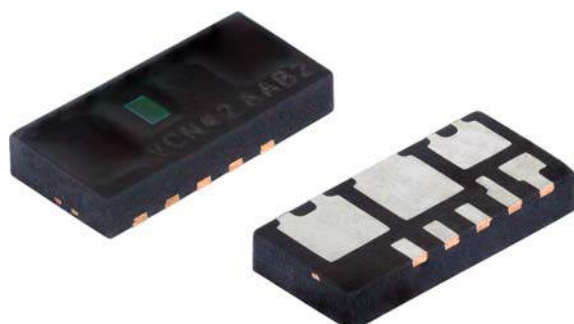


# Fully Integrated Proximity and Ambient Light Sensor With Infrared Emitter, I<sup>2</sup>C Interface, and Interrupt Function



22620

## DESCRIPTION

The VCNL4020 is a fully integrated proximity and ambient light sensor. Fully integrated means that the infrared emitter is included in the package. It has 16 bit resolution. It includes a signal processing IC and features standard I<sup>2</sup>C communication interface. It features an interrupt function.

## APPLICATIONS

- Proximity sensor for mobile devices (e.g. smart phones, touch phones, PDA, GPS) for touch screen locking, power saving, etc.
- Integrated ambient light function for display/keypad contrast control and dimming of mobile devices
- Proximity / optical switch for consumer, computing and industrial devices and displays
- Dimming control for consumer, computing and industrial displays

## FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 4.90 x 2.40 x 0.83
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS-PD), proximity sensor (PD), and signal conditioning IC
- Interrupt function
- Supply voltage range V<sub>DD</sub>: 2.5 V to 3.6 V
- Supply voltage range IR anode: 2.5 V to 5 V
- Communication via I<sup>2</sup>C interface
- I<sup>2</sup>C bus H-level range: 1.7 V to 5 V
- Floor life: 72 h, MSL 4, according to J-STD-020
- Low stand by current consumption: 1.5  $\mu$ A
- Material categorization: for definitions of compliance please see [www.vishay.com/doc?99912](http://www.vishay.com/doc?99912)



## PROXIMITY FUNCTION

- Built-in infrared emitter and photo-pin-diode for proximity function
- 16 bit effective resolution for proximity detection range ensures excellent cross talk immunity
- Programmable LED drive current from 10 mA to 200 mA in 10 mA steps
- Excellent ambient light suppression by signal modulation
- Proximity distance up to 200 mm

## AMBIENT LIGHT FUNCTION

- Built-in ambient light photo-pin-diode with close-to-human-eye sensitivity
- 16 bit dynamic range from 0.25 lx to 16 klx
- 100 Hz and 120 Hz flicker noise rejection

## PRODUCT SUMMARY

PART NUMBER	OPERATING RANGE (mm)	OPERATING VOLTAGE RANGE (V)	I <sup>2</sup> C BUS VOLTAGE RANGE (V)	LED PULSE CURRENT <sup>(1)</sup> (mA)	AMBIENT LIGHT RANGE (lx)	AMBIENT LIGHT RESOLUTION (lx)	OUTPUT CODE	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT
VCNL4020	1 to 200	2.5 to 3.6	1.7 to 5	10 to 200	0.25 to 16 383	0.25	16 bit, I <sup>2</sup> C	16 bit / 16 bit

### Note

<sup>(1)</sup> Adjustable through I<sup>2</sup>C interface

**ORDERING INFORMATION**

ORDERING CODE	PACKAGING	VOLUME <sup>(1)</sup>	REMARKS
VCNL4020-GS08	Tape and reel	MOQ: 3300 pcs	4.90 mm x 2.40 mm x 0.83 mm
VCNL4020-GS18		MOQ: 13 000 pcs	

**Note**

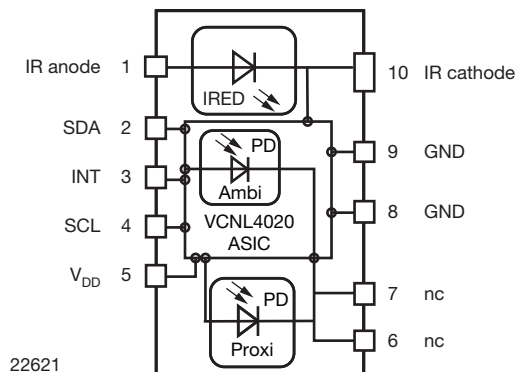
(1) MOQ: minimum order quantity

**ABSOLUTE MAXIMUM RATINGS** ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)

PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT
Supply voltage		$V_{DD}$	-0.3	5.5	V
Operation temperature range		$T_{amb}$	-25	+85	$^{\circ}\text{C}$
Storage temperature range		$T_{stg}$	-25	+85	$^{\circ}\text{C}$
Total power dissipation	$T_{amb} \leq 25\text{ }^{\circ}\text{C}$	$P_{tot}$		50	mW
Junction temperature		$T_j$		100	$^{\circ}\text{C}$

**BASIC CHARACTERISTICS** ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)

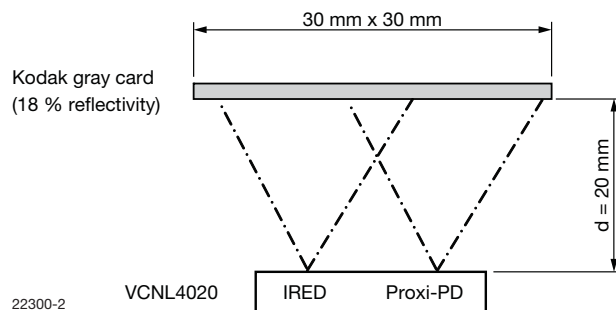
PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage $V_{DD}$			2.5		3.6	V
Supply voltage IR anode			2.5		5	V
I <sup>2</sup> C Bus H-level range			1.7		5	V
INT H-level range			1.7		5	V
INT low voltage	3 mA sink current				0.4	V
Current consumption	Standby current, no IRED-operation			1.5	2	$\mu\text{A}$
Current consumption proximity mode incl. IRED (averaged)	2 measurements per second, IRED current 20 mA			5		$\mu\text{A}$
	250 measurements per second, IRED current 20 mA			520		$\mu\text{A}$
	2 measurements per second, IRED current 200 mA			35		$\mu\text{A}$
	250 measurements per second, IRED current 200 mA			4		mA
Current consumption ambient light mode	2 measurements per second averaging = 1			2.5		$\mu\text{A}$
	8 measurements per second averaging = 1			10		$\mu\text{A}$
	2 measurements per second averaging = 64			160		$\mu\text{A}$
	8 measurements per second averaging = 64			640		$\mu\text{A}$
Ambient light resolution	Digital resolution (LSB count )			0.25		lx
Ambient light output	$E_V = 100\text{ lx}$ averaging = 64			400		counts
I <sup>2</sup> C clock rate range		$f_{SCL}$			3400	kHz

**CIRCUIT BLOCK DIAGRAM**


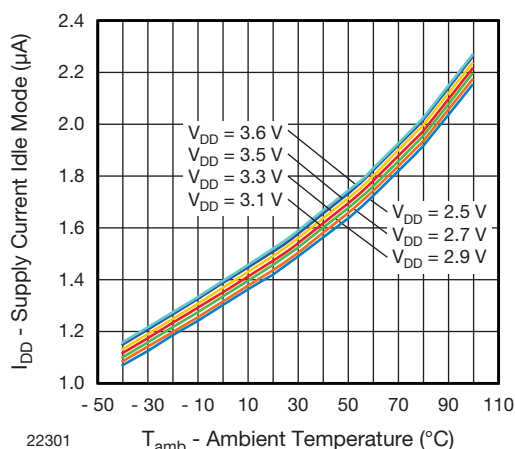
22621

**Note**

- nc must not be electrically connected  
Pads 6 and 7 are only considered as solder pads

**TEST CIRCUIT**


22300-2

**BASIC CHARACTERISTICS** ( $T_{amb} = 25\text{ }^{\circ}\text{C}$ , unless otherwise specified)


22301

Fig. 1 - Idle Current vs. Ambient Temperature

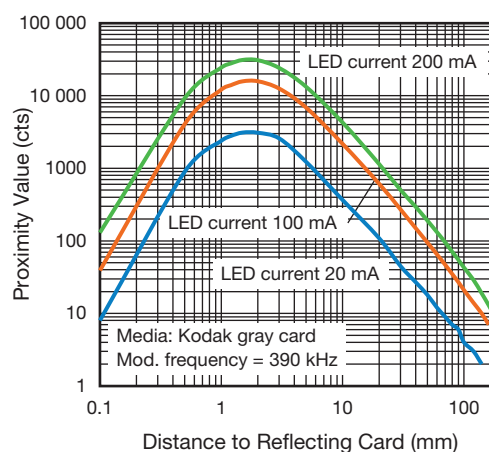
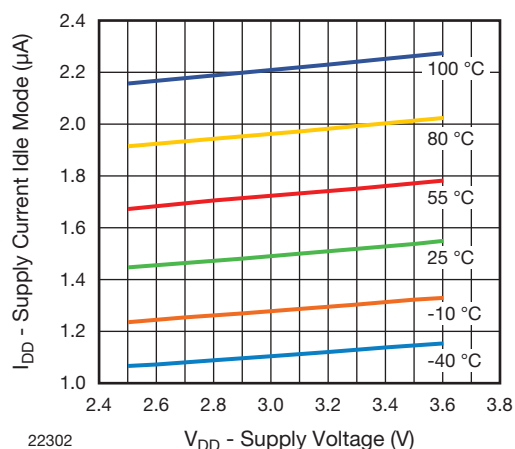
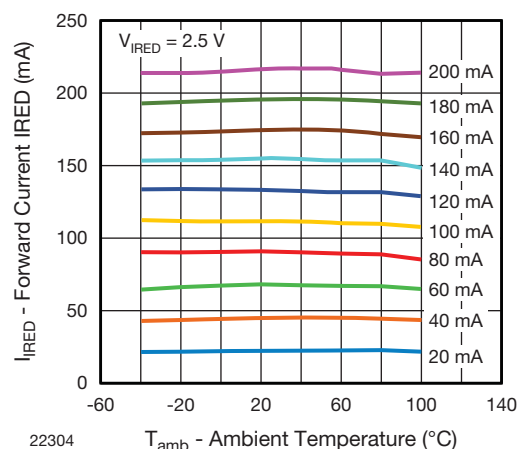


Fig. 3 - Proximity Value vs. Distance



22302

Fig. 2 - Idle Current vs.  $V_{DD}$ 


22304

Fig. 4 - Forward Current vs. Temperature

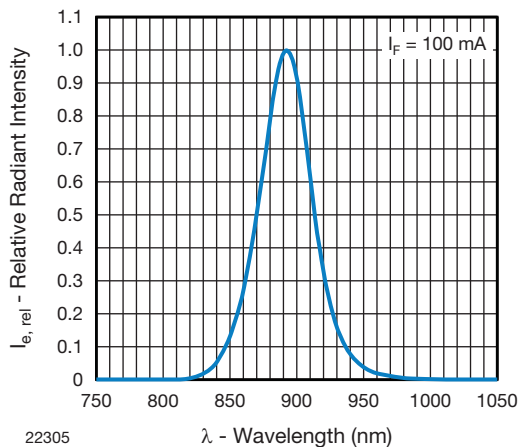


Fig. 5 - Relative Radiant Intensity vs. Wavelength

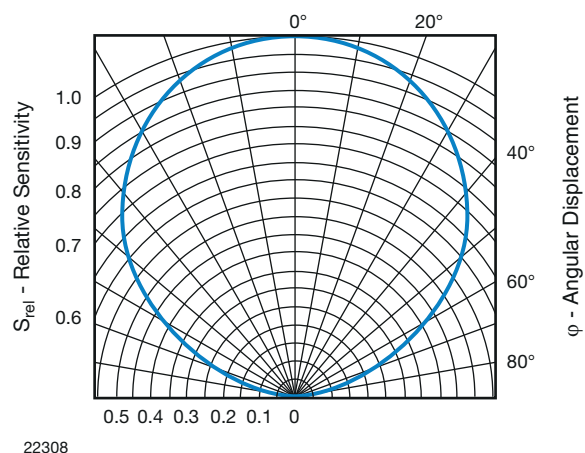


Fig. 8 - Relative Radiant Sensitivity vs. Angular Displacement (Proximity Sensor)

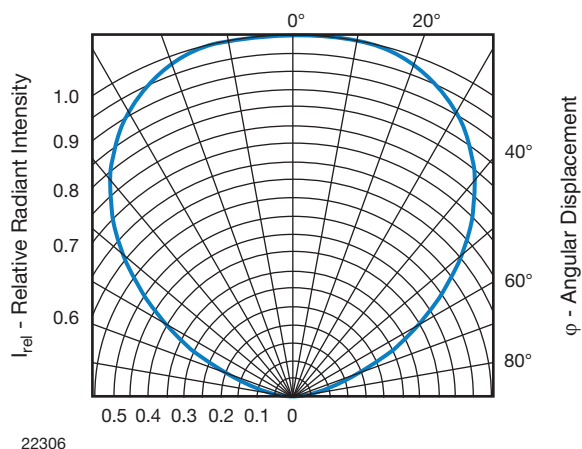


Fig. 6 - Relative Radiant Intensity vs. Angular Displacement

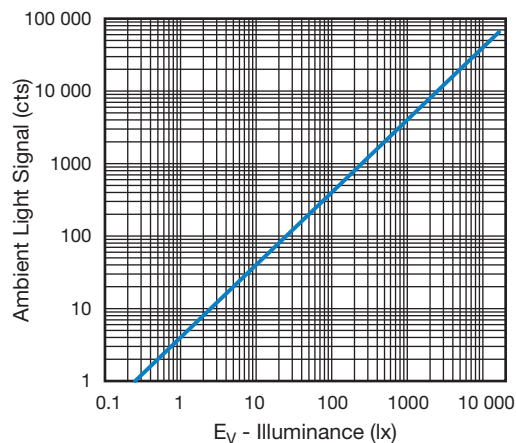


Fig. 9 - Ambient Light Value vs. Illuminance

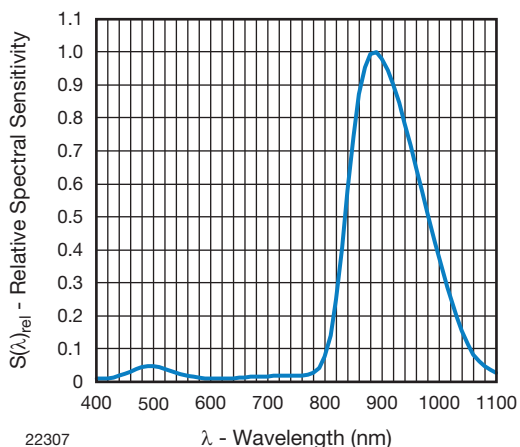


Fig. 7 - Relative Spectral Sensitivity vs. Wavelength (Proximity Sensor)

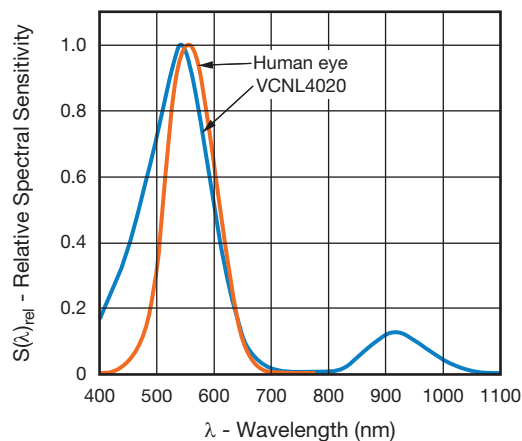
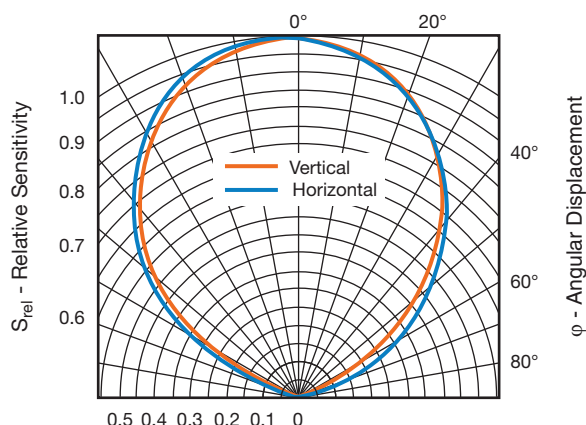


Fig. 10 - Relative Spectral Sensitivity vs. Wavelength (Ambient Light Sensor)



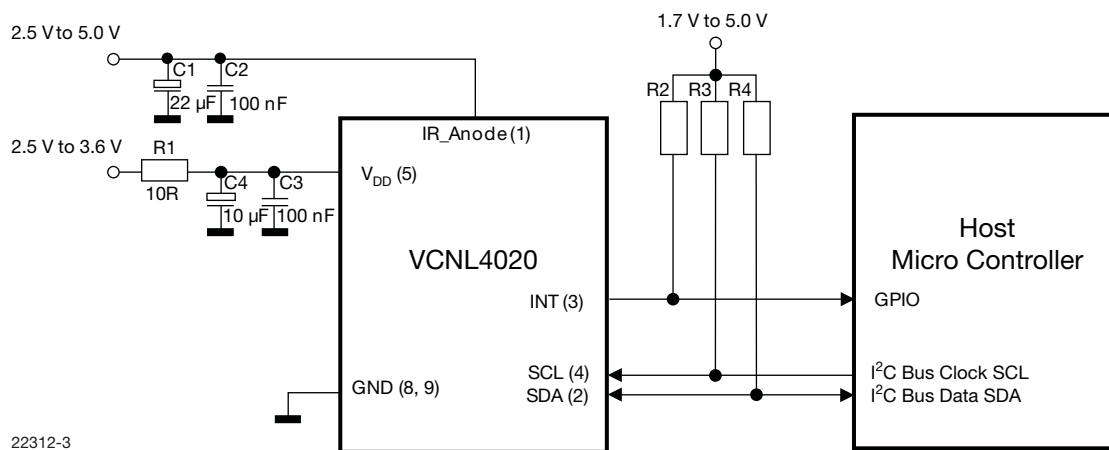
22311

Fig. 11 - Relative Radiant Sensitivity vs. Angular Displacement  
(Ambient Light Sensor)

## APPLICATION INFORMATION

VCNL4020 is a cost effective solution of proximity and ambient light sensor with I<sup>2</sup>C bus interface. The standard serial digital interface is easy to access “Proximity Signal” and “Light Intensity” without complex calculation and programming by external controller. Beside the digital output also a flexible programmable interrupt pin is available.

### 1. Application Circuit



22312-3

Fig. 12 - Application Circuit  
(x) = Pin Number

### Notes

- The interrupt pin is an open drain output. The needed pull-up resistor may be connected to the same supply voltage as the application controller and the pull-up resistors at SDA/SCL. Proposed value R2 should be >1 k $\Omega$ , e.g. 10 k $\Omega$  to 100 k $\Omega$ . Proposed value for R3 and R4, e.g. 2.2 k $\Omega$  to 4.7 k $\Omega$ , depend also on the I<sup>2</sup>C bus speed. For detailed description about set-up and use of the interrupt as well as more application related information see AN: “Designing VCNL4020 into an Application”.
- IR\_Cathode needs no external connection. The needed connection to the driver is done internally.

## 2. I<sup>2</sup>C Interface

The VCNL4020 contains seventeen 8 bit registers for operation control, parameter setup and result buffering. All registers are accessible via I<sup>2</sup>C communication. Figure 13 shows the basic I<sup>2</sup>C communication with VCNL4020.

The built in I<sup>2</sup>C interface is compatible with all I<sup>2</sup>C modes (standard, fast and high speed).

I<sup>2</sup>C H-level range = 1.7 V to 5 V.

Please refer to the I<sup>2</sup>C specification from NXP for details.

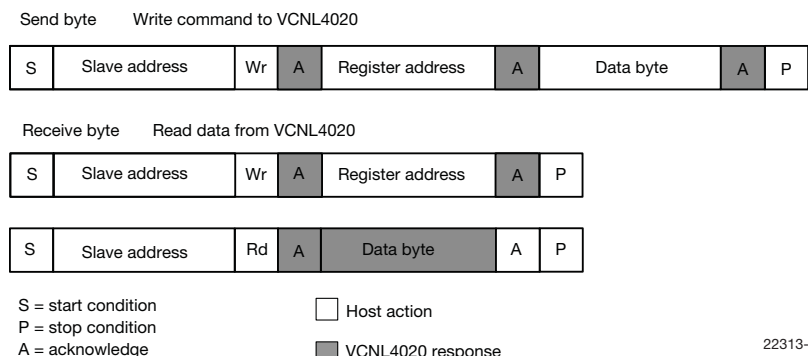


Fig. 13 - Send Byte/Receive Byte Protocol

### Device Address

The VCNL4020 has a fix slave address for the host programming and accessing selection. The predefined 7 bit I<sup>2</sup>C bus address is set to 0010 011 = 13h. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0010 011x = 26h for write, 27h for read.

### Register Addresses

VCNL4020 has seventeen user accessible 8 bit registers. The register addresses are 80h (register #0) to 90h (register #16).

## REGISTER FUNCTIONS

### Register #0 Command Register

Register address = 80h

The register #0 is for starting ambient light or proximity measurements. This register contains 2 flag bits for data ready indication.

TABLE 1 - COMMAND REGISTER #0							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
config_lock	als_data_rdy	prox_data_rdy	als_od	prox_od	als_en	prox_en	selftimed_en
Description							
config_lock	Read only bit. Value = 1						
als_data_rdy	Read only bit. Value = 1 when ambient light measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #5, reg #6) is read.						
prox_data_rdy	Read only bit. Value = 1 when proximity measurement data is available in the result registers. This bit will be reset when one of the corresponding result registers (reg #7, reg #8) is read.						
als_od	R/W bit. Starts a single on-demand measurement for ambient light. If averaging is enabled, starts a sequence of readings and stores the averaged result. Result is available at the end of conversion for reading in the registers #5(HB) and #6(LB).						
prox_od	R/W bit. Starts a single on-demand measurement for proximity. Result is available at the end of conversion for reading in the registers #7(HB) and #8(LB).						
als_en	R/W bit. Enables periodic als measurement						
prox_en	R/W bit. Enables periodic proximity measurement						
selftimed_en	R/W bit. Enables state machine and LP oscillator for self timed measurements; no measurement is performed until the corresponding bit is set						

### Note

- With setting bit 3 and bit 4 at the same write command, a simultaneously measurement of ambient light and proximity is done. Beside als\_en and/or prox\_en first selftimed\_en needs to be set. On-demand measurement modes are disabled if selftimed\_en bit is set. For the selftimed\_en mode changes in reading rates (reg #4 and reg #2) can be made only when b0 (selftimed\_en bit) = 0. For the als\_od mode changes to the reg #4 can be made only when b4 (als\_od bit) = 0; this is to avoid synchronization problems and undefined states between the clock domains. In effect this means that it is only reasonable to change rates while no selftimed conversion is ongoing.

**Register #1 Product ID Revision Register**

Register address = 81h. This register contains information about product ID and product revision.

Register data value of current revision = 21h.

**TABLE 2 - PRODUCT ID REVISION REGISTER #1**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Product ID				Revision ID			
Description							
Product ID		Read only bits. Value = 2					
Revision ID		Read only bits. Value = 1					

**Register #2 Rate of Proximity Measurement**

Register address = 82h.

**TABLE 3 - PROXIMITY RATE REGISTER #2**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n/a					Rate of Proximity Measurement (no. of measurements per second)		
Description							
Proximity rate		R/W bits. 000 - 1.95 measurements/s (DEFAULT) 001 - 3.90625 measurements/s 010 - 7.8125 measurements/s 011 - 16.625 measurements/s 100 - 31.25 measurements/s 101 - 62.5 measurements/s 110 - 125 measurements/s 111 - 250 measurements/s					

**Note**

- If self\_timed measurement is running, any new value written in this register will not be taken over until the mode is actually cycled.

**Register #3 LED Current Setting for Proximity Mode**

Register address = 83h. This register is to set the LED current value for proximity measurement.

The value is adjustable in steps of 10 mA from 0 mA to 200 mA.

This register also contains information about the used device fuse program ID.

**TABLE 4 - IR LED CURRENT REGISTER #3**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Fuse prog ID		IR LED current value					
Description							
Fuse prog ID		Read only bits. Information about fuse program revision used for initial setup/calibration of the device.					
IR LED current value		R/W bits. IR LED current = Value (dec.) x 10 mA. Valid Range = 0 to 20d. e.g. 0 = 0 mA , 1 = 10 mA, ..., 20 = 200 mA (2 = 20 mA = DEFAULT) LED Current is limited to 200 mA for values higher as 20d.					



**Register #4 Ambient Light Parameter Register**

Register address = 84h.

TABLE 5 - AMBIENT LIGHT PARAMETER REGISTER #4							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Cont. conv. mode	als_rate			Auto offset compensation	Averaging function (number of measurements per run)		
Description							
Cont. conversion mode	R/W bit. Continuous conversion mode. Enable = 1; Disable = 0 = DEFAULT This function can be used for performing faster ambient light measurements. This mode should only be used with ambient light on-demand measurements. Do not use with self-timed mode. Please refer to the application information chapter 3.3 for details about this function.						
Ambient light measurement rate	R/W bits. Ambient light measurement rate 000 - 1 samples/s 001 - 2 samples/s = DEFAULT 010 - 3 samples/s 011 - 4 samples/s 100 - 5 samples/s 101 - 6 samples/s 110 - 8 samples/s 111 - 10 samples/s						
Auto offset compensation	R/W bit. Automatic offset compensation. Enable = 1 = DEFAULT; Disable = 0 In order to compensate a technology, package or temperature related drift of the ambient light values there is a built in automatic offset compensation function. With active auto offset compensation the offset value is measured before each ambient light measurement and subtracted automatically from actual reading.						
Averaging function	R/W bits. Averaging function. Bit values sets the number of single conversions done during one measurement cycle. Result is the average value of all conversions. Number of conversions = 2 <sup>decimal_value</sup> e.g. 0 = 1 conv., 1 = 2 conv, 2 = 4 conv., ....7 = 128 conv. DEFAULT = 32 conv. (bit 2 to bit 0: 101)						

**Note**

- If self\_timed measurement is running, any new value written in this register will not be taken over until the mode is actually cycled.

**Register #5 and #6 Ambient Light Result Register**

Register address = 85h and 86h. These registers are the result registers for ambient light measurement readings.

The result is a 16 bit value. The high byte is stored in register #5 and the low byte in register #6.

TABLE 6 - AMBIENT LIGHT RESULT REGISTER #5							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
Read only bits. High byte (15:8) of ambient light measurement result							

TABLE 7 - AMBIENT LIGHT RESULT REGISTER #6							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
Read only bits. Low byte (7:0) of ambient light measurement result							



**Register #7 and #8 Proximity Measurement Result Register**

Register address = 87h and 88h. These registers are the result registers for proximity measurement readings.

The result is a 16 bit value. The high byte is stored in register #7 and the low byte in register #8.

**TABLE 8 - PROXIMITY RESULT REGISTER #7**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
<b>Description</b>							
Read only bits. High byte (15:8) of proximity measurement result							

**TABLE 9 - PROXIMITY RESULT REGISTER #8**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
<b>Description</b>							
Read only bits. Low byte (7:0) of proximity measurement result							

**Register #9 Interrupt Control Register**

Register address = 89h.

**TABLE 10 - INTERRUPT CONTROL REGISTER #9**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Int count exceed			n/a	INT_PROX_ready_EN	INT_ALS_ready_EN	INT_THRES_EN	INT_THRES_SEL
<b>Description</b>							
Int count exceed		R/W bits. These bits contain the number of consecutive measurements needed above/below the threshold 000 - 1 count = DEFAULT 001 - 2 count 010 - 4 count 011 - 8 count 100 - 16 count 101 - 32 count 110 - 64 count 111 - 128 count					
INT_PROX_ready_EN		R/W bit. Enables interrupt generation at proximity data ready					
INT_ALS_ready_EN		R/W bit. Enables interrupt generation at ambient data ready					
INT_THRES_EN		R/W bit. Enables interrupt generation when high or low threshold is exceeded					
INT_THRES_SEL		R/W bit. If 0: thresholds are applied to proximity measurements If 1: thresholds are applied to als measurements					

**Register #10 and #11 Low Threshold**

Register address = 8Ah and 8Bh. These registers contain the low threshold value. The value is a 16 bit word. The high byte is stored in register #10 and the low byte in register #11.

**TABLE 11 - LOW THRESHOLD REGISTER #10**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
R/W bits. High byte (15:8) of low threshold value							

**TABLE 12 - LOW THRESHOLD REGISTER #11**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
R/W bits. Low byte (7:0) of low threshold value							

**Register #12 and #13 High Threshold**

Register address = 8Ch and 8Dh. These registers contain the high threshold value. The value is a 16 bit word. The high byte is stored in register #12 and the low byte in register #13.

**TABLE 13 - HIGH THRESHOLD REGISTER #12**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
R/W bits. High byte (15:8) of high threshold value							

**TABLE 14 - HIGH THRESHOLD REGISTER #13**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Description							
R/W bits. Low byte (7:0) of high threshold value							

**Register #14 Interrupt Status Register**

Register address = 8Eh. This register contains information about the interrupt status for either proximity or ALS function and indicates if high or low going threshold exceeded.

**TABLE 15 - INTERRUPT STATUS REGISTER #14**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
n/a				int_prox_ready	int_als_ready	int_th_low	int_th_hi
Description							
int_prox_ready		R/W bit. Indicates a generated interrupt for proximity					
int_als_ready		R/W bit. Indicates a generated interrupt for als					
int_th_low		R/W bit. Indicates a low threshold exceed					
int_th_hi		R/W bit. Indicates a high threshold exceed					

**Note**

- Once an interrupt is generated the corresponding status bit goes to 1 and stays there unless it is cleared by writing a 1 in the corresponding bit. The int pad will be pulled down while at least one of the status bit is 1.

**Register #15 Proximity Modulator Timing Adjustment**

Register address = 8Fh.

TABLE 16 - PROXIMITY MODULATOR TIMING ADJUSTMENT #15							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Modulation delay time			Proximity frequency		Modulation dead time		
Description							
Modulation delay time		R/W bits. Setting a delay time between IR LED signal and IR input signal evaluation. This function is for compensation of delays from IR LED and IR photo diode. Also in respect to the possibility for setting different proximity signal frequency. Correct adjustment is optimizing measurement signal level. ( DEFAULT = 0)					
Proximity frequency		R/W bits. Setting the proximity IR test signal frequency The proximity measurement is using a square IR signal as measurement signal. Four different values are possible: 00 = 390.625 kHz (DEFAULT) 01 = 781.25 kHz 10 = 1.5625 MHz 11 = 3.125 MHz					
Modulation dead time		R/W bits. Setting a dead time in evaluation of IR signal at the slopes of the IR signal. ( DEFAULT = 1) This function is for reducing of possible disturbance effects. This function is reducing signal level and should be used carefully.					

**Note**

- The settings for best performance will be provided by Vishay. With first samples this is evaluated to:  
Delay Time = 0 ; Dead Time = 1 and Prox Frequency = 0 . With that register#15 should be programmed with 1 (= default value).

**Register #16 Ambient IR Light Level Register**

Register address = 90h.

This register is not intended to be used by customer.

**3. IMPORTANT APPLICATION HINTS AND EXAMPLES**
**3.1 Receiver standby mode**

In standby mode the receiver has the lowest current consumption of about 1.5  $\mu$ A. In this mode only the I<sup>2</sup>C interface is active. This is always valid, when there are no measurement demands for proximity and ambient light executed. Also the current sink for the IR-LED is inactive, so there is no need for changing register #3 (IR LED current).

**3.2 Data Read**

In order to get a certain register value, the register has to be addressed without data like shown in the following scheme. After this register addressing, the data from the addressed register is written after a subsequent read command.

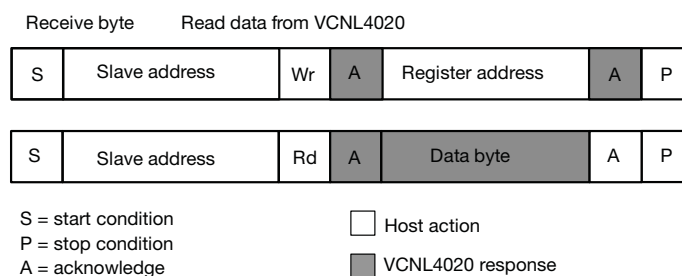


Fig. 14 - Send Byte/Receive Byte Protocol

The stop condition between these write and read sequences is not mandatory. It works also with a repeated start condition.

**Note**

- For reading out 2 (or more) subsequent registers like the result registers, it is not necessary to address each of the registers separately. After one read command the internal register counter is increased automatically and any subsequent read command is accessing the next register.

Example: read register “Ambient Light Result Register” #5 and #6:

Addressing:command: 26h, 85h (VCNL4020\_I<sup>2</sup>C\_Bus\_Write\_Adr., Ambient Light Result Register #5 [85])

Read register #5:command: 27h, data (VCNL4020\_I<sup>2</sup>C\_Bus\_Read\_Adr., {High Byte Data of Ambient Light Result register #5 [85]})

Read register #6:command: 27h, data (VCNL4020\_I<sup>2</sup>C\_Bus\_Read\_Adr., {Low Byte Data of Ambient Light Result register #6 [86]})

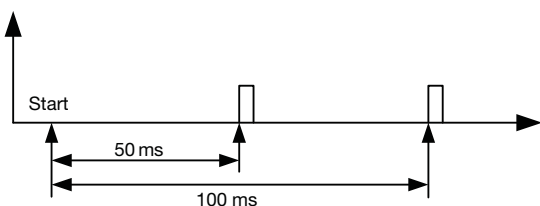
### 3.3 Continuous Conversion Mode in Ambient Light Measurement

In the following is a detail description of the function “continuous conversion” (bit 7 of register #4)

#### Standard mode (bit 7 of reg #4 = 0):

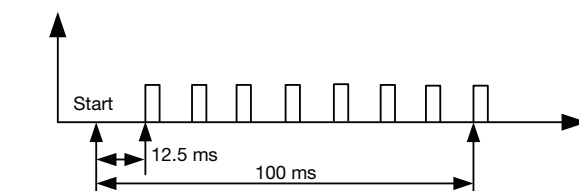
In standard mode the ambient light measurement is done during a fixed time frame of 100 ms. The single measurement itself takes actually only appr. 300  $\mu$ s.

The following figures show examples of this measurement timing in standard mode using averaging function 2 and 8 as examples for illustration (possible values up to 128).



22315

Fig. 15 - Ambient Light Measurement with Averaging = 2;  
Final Measurement Result = Average of these 2 Measurements



22316

Fig. 16 - Ambient Light Measurement with Averaging = 8;  
Final Measurement Result = Average of these 8 Measurements

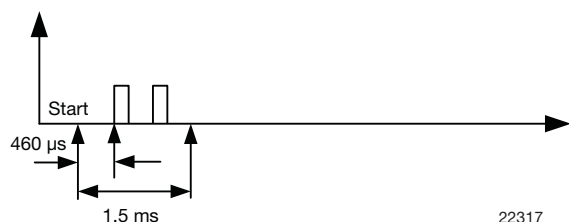
#### Note

- $\geq$  Independent of setting of averaging the result is available only after 100 ms.

#### Continuous conversion mode (bit 7 of register #4 = 1):

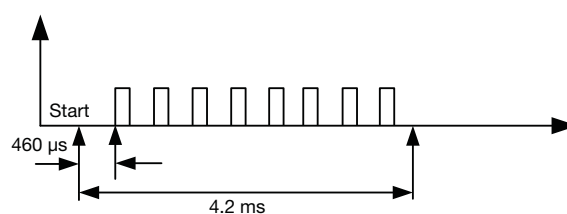
In continuous conversion mode the single measurements are done directly subsequent after each other.

See following examples in figure 17 and 18



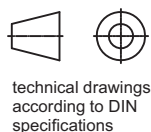
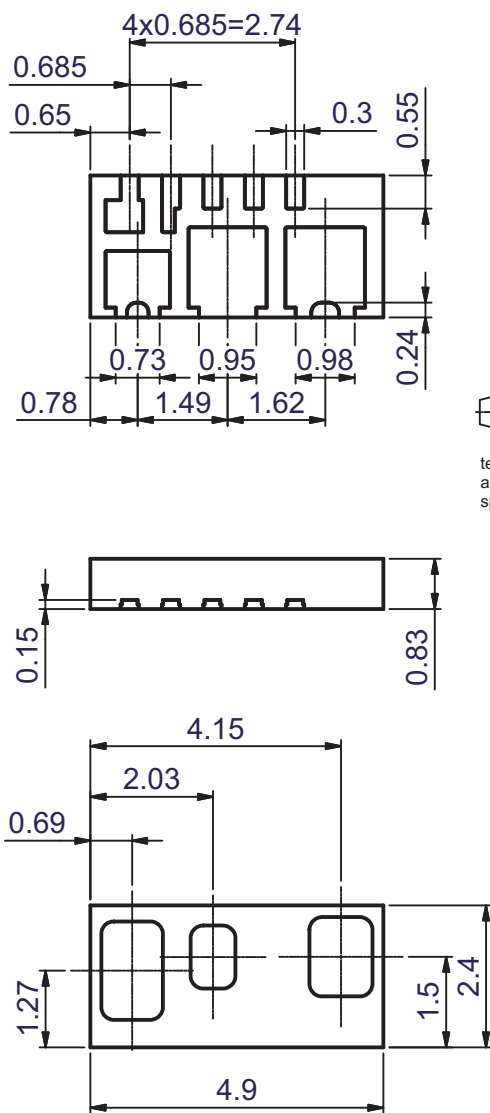
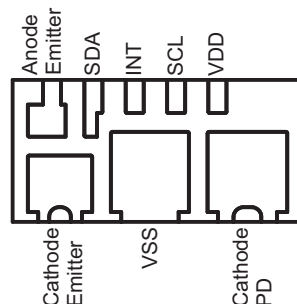
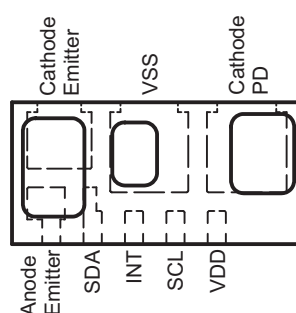
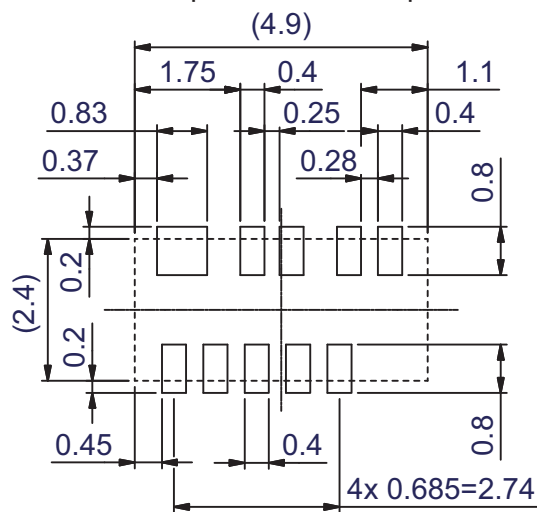
22317

Fig. 17 - Ambient Light Measurement with Averaging = 2;  
using Continuous Conversion Mode



22318

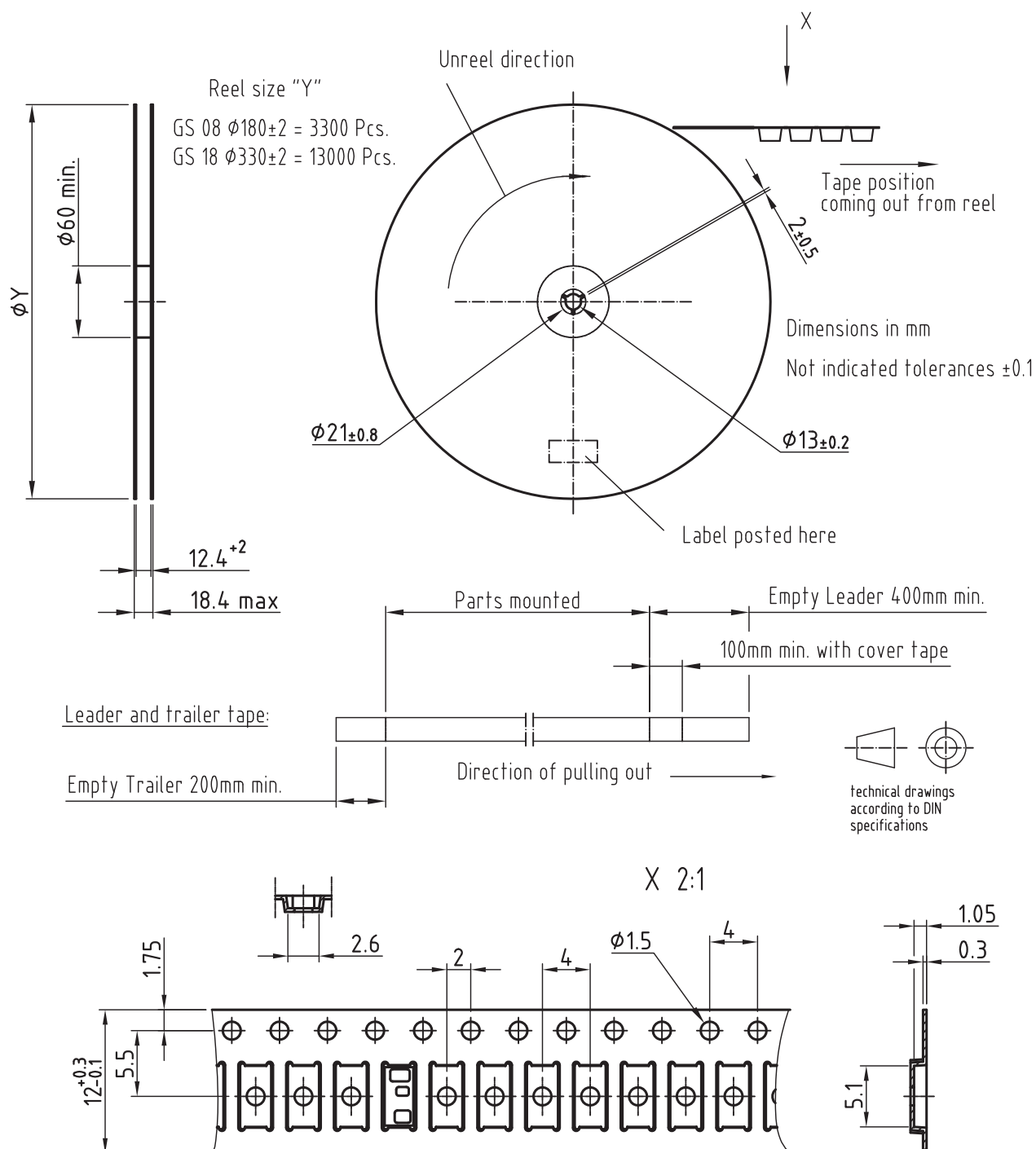
Fig. 18 - Ambient Light Measurement with Averaging = 8;  
using Continuous Conversion Mode

**PACKAGE DIMENSIONS** in millimeters

**Pinning Bottom view**

**Pinning Top view**

**Proposed PCB Footprint**


Drawing-No.: 6.550-5319

Not indicated tolerances  $\pm 0.1$

### TAPE AND REEL DIMENSIONS in millimeters



Drawing-No.: 9.700-5387.01-4

## SOLDER PROFILE

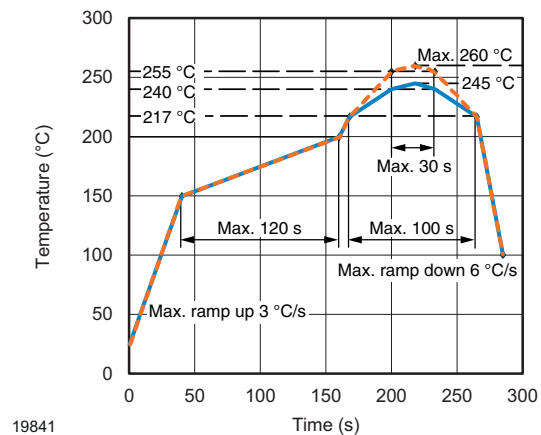


Fig. 19 - Lead (Pb)-free Reflow Solder Profile  
According to J-STD-020

## DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

## FLOOR LIFE

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 72 h

Conditions:  $T_{amb} < 30\text{ °C}$ , RH < 60 %

Moisture sensitivity level 4, according to J-STD-020.

## DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at 40 °C (+ 5 °C), RH < 5 %.





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